

A characterisation of R_1 -spaces via a Mal'tsev condition

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Introduction

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Categorical algebra studies algebras by working in a category satisfying certain axioms.

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- Mal'tsev and protomodular categories;
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- abelian categories.

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- abelian categories.

One may ask: of which of these types of categories is a given category of spaces an example?

For example, consider **Top**, and the notion of regular category.

Definition (Barr, Grillet and van Osdol, 1971)

A category \mathbb{C} is called *regular* if it has finite limits and admits a pullback-stable (regular epi, mono)-factorisation system.

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Examples of regular categories include **Set** and moreover, any variety of universal algebras. However, **Top** is *not* regular because quotient maps are not pullback-stable.

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On the other hand, \mathbf{Top}^{op} , is regular. Let us then consider \mathbf{Top}^{op} instead, and ask which axioms it satisfies. In this talk, we consider the notion of Mal'tsev category, and show that

- \mathbf{Top}^{op} is not a Mal'tsev category;
- however, it (and moreover, any regular category) has a largest full subcategory which is (in a certain sense);

On the other hand, \mathbf{Top}^{op} , is regular. Let us then consider \mathbf{Top}^{op} instead, and ask which axioms it satisfies. In this talk, we consider the notion of Mal'tsev category, and show that

- \mathbf{Top}^{op} is not a Mal'tsev category;
- however, it (and moreover, any regular category) has a largest full subcategory which is (in a certain sense);
- moreover, we show that the objects of this subcategory are characterised by a known separation axiom – they are the so-called R_1 -spaces.

Mal'tsev varieties

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Theorem (Mal'tsev, 1954)

For a variety \mathbb{X} of universal algebras, the following are equivalent:

- *the composition of congruences on any object in \mathbb{X} is commutative;*
- *the algebraic theory of \mathbb{X} contains a ternary term μ satisfying*

$$\mu(x, y, y) = x = \mu(y, y, x).$$

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For example, the variety of all groups satisfies this condition: take $\mu(x, y, z) = x - y + z$.

Naturally Mal'tsev categories

One way to generalize Mal'tsev varieties to categories is as follows:

Definition (Johnstone, 1977)

A category \mathbb{C} is called a *naturally Mal'tsev category* if the identity functor $1_{\mathbb{C}}$ admits an internal Mal'tsev operation μ in the functor category $\text{Fun}(\mathbb{C}, \mathbb{C})$.

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This is a very strong condition: for example, a pointed variety of universal algebras is a naturally Mal'tsev category if and only if it is abelian (i.e. it is the variety of R -modules for some ring R).

Other equivalent conditions

The conditions in the theorem are also equivalent to each of the following:

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- every reflexive internal relation is an equivalence relation (where by an *internal relation* we mean a relation from A to B which is a subalgebra of $A \times B$);
- every internal relation R from A to B is *difunctional*, i.e. it satisfies

$$(x_1 R y_2 \wedge x_2 R y_2 \wedge x_2 R y_1) \Rightarrow x_1 R y_1.$$

This second condition is due to Lambek (1957).

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Definition

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Given any internal relation $r : R \rightarrow A \times B$ in a category \mathbb{C} , and an object S in \mathbb{C} , there is a corresponding relation on hom-sets:

$$\text{Hom}(S, r) : \text{Hom}(S, R) \rightarrow \text{Hom}(S, A) \times \text{Hom}(S, B)$$

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We call an internal relation *reflexive*, *transitive*, *symmetric*, *difunctional* ... when for every S , the relation above is *reflexive*, *transitive*, *symmetric*, *difunctional* ... in the usual set-theoretic sense.

Relations in categories

Notation: If we have an internal relation $R \rightarrow X \times Y$ and two morphism $x : S \rightarrow X$ and $y : S \rightarrow Y$, we will write xRy to mean that x and y are related by the relation

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$$\text{Hom}(S, r) : \text{Hom}(S, R) \rightarrow \text{Hom}(S, X) \times \text{Hom}(S, Y).$$

This is equivalent to the existence of a morphism f such that the diagram commutes:

A commutative diagram with three nodes: R at the top left, $X \times Y$ at the top right, and S at the bottom center. A solid arrow labeled r points from R to $X \times Y$. A solid arrow labeled (x, y) points from S to $X \times Y$. A dotted arrow labeled f points from S to R .

Mal'tsev categories

Definition (Carboni, Lambek and Pedicchio, 1990)

A *Mal'tsev category* is a category in which every internal relation is difunctional.

That is, a Mal'tsev category is a category in which every object S in \mathbb{C} satisfies:

(D) for every internal relation R in \mathbb{C} , the relation $\text{Hom}(S, R)$ between hom-sets is difunctional.

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Question: Is \mathbf{Top}^{op} a Mal'tsev category?

Answer: No. One can construct a non-difunctional co-relation using the Sierpiński space.

Condition (D)

Recall the condition on the previous slide:

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Theorem

Let \mathbb{C} be a regular category admitting binary coproducts. Then $D(\mathbb{C})$, the full subcategory of all objects satisfying condition (D), is the largest full subcategory of \mathbb{C} which is Mal'tsev and which is closed under regular quotients and binary coproducts in \mathbb{C} .

Note that $D(\mathbb{C})$ is closed under regular quotients and binary coproducts because the Yoneda embedding $Y : \mathbb{C}^{\text{op}} \rightarrow \mathbf{Set}^{\mathbb{C}}$ takes colimits to limits. Thus a colimit/regular quotient of objects in $D(\mathbb{C})$ takes each internal relation to a limit/regular subobject of difunctional relations, which will itself be difunctional.

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To show that $D(\mathbb{C})$ is the largest such category, we need the following lemma.

Lemma

For a regular category \mathbb{C} admitting binary coproducts and an object S in \mathbb{C} , the following are equivalent:

- (a) S satisfies (D);
- (b) $\iota_1 R' \iota_1$, where $\iota_1 : S \rightarrow 2S$ is the first coproduct injection and (R', r'_1, r'_2) is the relation from $2S$ to $2S$ appearing in the (regular epi, mono)-factorisation of the vertical morphism in the following diagram:

$$\begin{array}{ccc}
 3S & & \begin{pmatrix} k'_1 \\ k'_2 \\ k'_3 \end{pmatrix} \\
 \downarrow & \searrow & \downarrow \\
 \begin{pmatrix} \iota_1 & \iota_2 \\ \iota_2 & \iota_2 \\ \iota_2 & \iota_1 \end{pmatrix} & & R' \\
 & \swarrow & \downarrow \\
 2S \times 2S & & r' = (r'_1, r'_2)
 \end{array} \tag{1}$$

This lemma is adapted from a theorem due to Bourn and Z. Janelidze. One direction is easy to show: if we consider the relation R' below:

$$\begin{array}{ccc}
 3S & & \begin{pmatrix} k'_1 \\ k'_2 \\ k'_3 \end{pmatrix} \\
 \downarrow & \searrow & \downarrow \\
 \begin{pmatrix} \iota_1 & \iota_2 \\ \iota_2 & \iota_2 \\ \iota_2 & \iota_1 \end{pmatrix} & & R' \\
 & \swarrow & \downarrow \\
 2S \times 2S & & r' = (r'_1, r'_2)
 \end{array} \tag{2}$$

then we have $\iota_1 R' \iota_2$, $\iota_2 R' \iota_2$ and $\iota_2 R' \iota_1$, so $\iota_1 R' \iota_1$ if $\text{Hom}(S, R')$ is difunctional.

Conversely, given a relation $R \rightarrow X \times Y$ for which $x_1 R y_2$, $x_2 R y_2$ and $x_2 R y_1$, consider the pullback.

$$\begin{array}{ccc}
 R'' & \xrightarrow{p} & R \\
 \downarrow r''=(r_1'', r_2'') & & \downarrow r=(r_1, r_2) \\
 2S \times 2S & \xrightarrow{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \times \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}} & X \times Y
 \end{array} \tag{3}$$

Conversely, given a relation $R \rightarrow X \times Y$ for which $x_1 R y_2$, $x_2 R y_2$ and $x_2 R y_1$, consider the pullback.

$$\begin{array}{ccc}
 R'' & \xrightarrow{p} & R \\
 \downarrow r''=(r_1'', r_2'') & & \downarrow r=(r_1, r_2) \\
 2S \times 2S & \xrightarrow{\begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix}} & X \times Y
 \end{array} \tag{4}$$

By construction of R'' we have that $\iota_1 R'' \iota_2$, $\iota_2 R'' \iota_2$ and $\iota_2 R'' \iota_1$, so that R'' contains the relation R' from the theorem.

Conversely, given a relation $R \rightarrow X \times Y$ for which $x_1 R y_2$, $x_2 R y_2$ and $x_2 R y_1$, consider the pullback.

$$\begin{array}{ccc}
 R'' & \xrightarrow{p} & R \\
 \downarrow r''=(r_1'', r_2'') & & \downarrow r=(r_1, r_2) \\
 2S \times 2S & \xrightarrow{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \times \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}} & X \times Y
 \end{array} \tag{4}$$

By construction of R'' we have that $\iota_1 R'' \iota_2$, $\iota_2 R'' \iota_2$ and $\iota_2 R'' \iota_1$, so that R'' contains the relation R' from the theorem. But then $\iota_1 R'' \iota_1$, and we obtain $x_1 R y_1$ as required.

Let us return to \mathbf{Top}^{op} . What we have shown is that:

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Topological spaces

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- \mathbf{Top}^{op} is not a Mal'tsev category,
- but it admits a largest full subcategory $D(\mathbf{Top}^{\text{op}})$ which is;
- moreover, we can test to see if an object is in this subcategory, by checking for a relation between two particular morphisms – i.e. the existence of a certain morphism.

Test for the dual of (D)

Following the theorem, a space S satisfies the dual of (D) if and only if there is a continuous map f which makes the diagram commute:

$$\begin{array}{ccc} & S^3 & \\ & \uparrow & \swarrow (k_1, k_2, k_3) \\ \begin{pmatrix} \pi_1 & \pi_2 & \pi_2 \\ \pi_2 & \pi_2 & \pi_1 \end{pmatrix} & & R' \\ & \nearrow r' & \searrow \text{---} f \text{---} \\ S^2 + S^2 & \xrightarrow{\begin{pmatrix} \pi_1 \\ \pi_1 \end{pmatrix}} & S \end{array}$$

where R' is the subspace of S^3 which is the image of the vertical map, i.e. the subspace

$$\{(x, y, z) \mid x = y \vee y = z\}$$

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The map f is uniquely defined if it exists, so it is enough to check continuity.

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Lemma

The map f is continuous if and only if S is an R_1 -space in the sense of Davis (1961), i.e. satisfies the following separation axiom:

(R_1) for all $x, y \in X$, if there exists an open set A such that $x \in A$ and $y \notin A$, then there exists disjoint open sets B and C such that $x \in B$ and $y \in C$.

Proof

As a set map, $f : R' \rightarrow S$ takes a triple (x, y, z) to x if $y = z$ and to z if $x = y$.

As a set map, $f : R' \rightarrow S$ takes a triple (x, y, z) to x if $y = z$ and to z if $x = y$.

(\Rightarrow): Suppose f is continuous. Let A be an open set with $x \in A$ and $y \notin A$. Then

$$f^{-1}(A) = \{(x, y, z) \mid (x = y \wedge z \in A) \vee (y = z \wedge x \in A)\}$$

is open in R' . Thus there exist open sets U , W and V in S such that $(x, y, y) \in U \times W \times V \cap R' \subseteq f^{-1}(A)$. But (z, z, y) can never be in $f^{-1}(A)$ for any z – otherwise $y \in A$! Thus U and W do not intersect, and x and y are separated by neighbourhoods as required.

(\Leftarrow): Suppose S is an R_1 -space and let A be open in S with $(x, y, y) \in f^{-1}(A)$. If $y \in A$, then

$$(x, y, y) \in A \times A \times A \cap R' \subseteq f^{-1}(A).$$

Otherwise, pick open sets $x \in U$ and $y \in V$ such that $U \cap V = \emptyset$ and note that

$$(x, y, y) \in U \times V \times V \cap R' \subseteq f^{-1}(A)$$

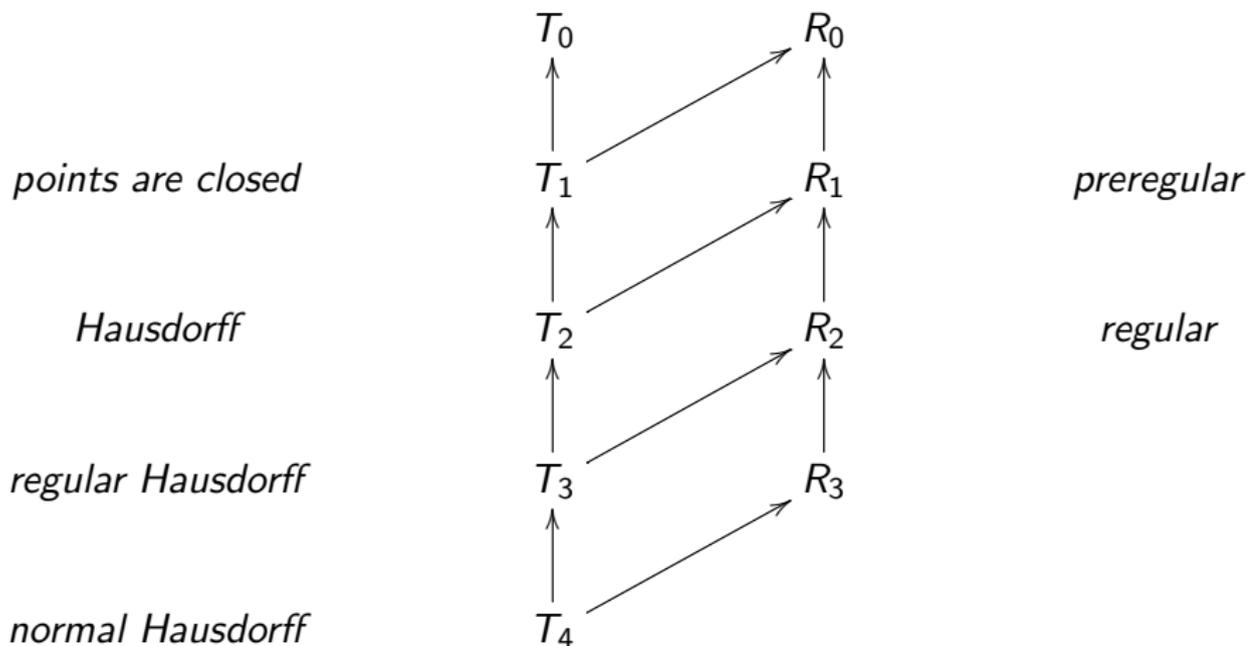
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R_1 -spaces

Where do R_1 -spaces fit in?

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Concluding remarks

We have presented a connection between two notions:

- the notion of a Mal'tsev variety, or term, and
- the notion of an R_1 -space.

via the language of categories.

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A natural question is: do other such connections exist?

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- Other term conditions from algebra can be translated this way: for example, the case for a binary subtraction term has been considered by Z. Janelidze (in fact that result predates this one).
- Work on finding relational conditions for other separation axioms is still in progress (e.g. R_0 and regular spaces).

Thank you.